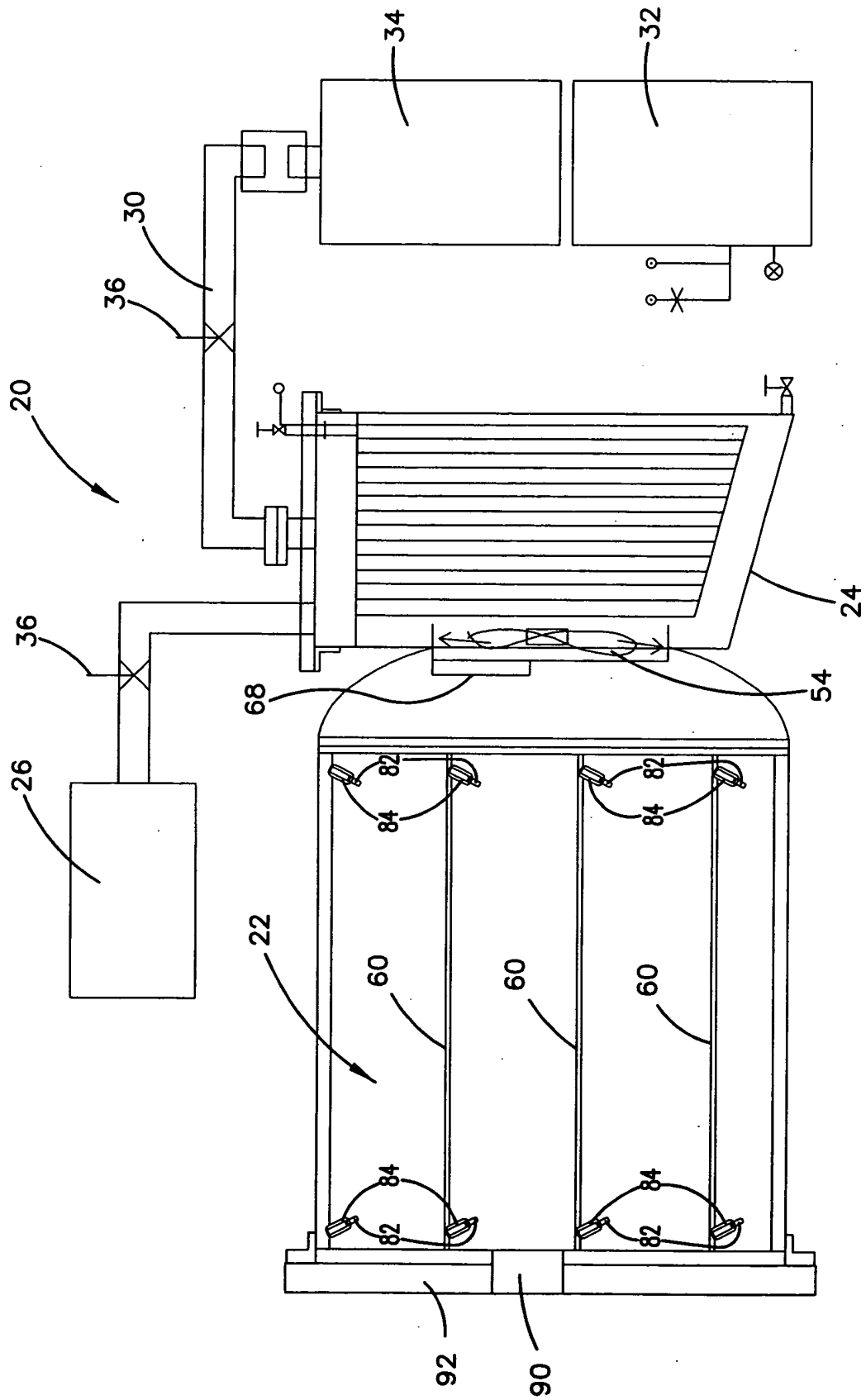


FIG. 1



The diagram illustrates a multi-camera system for monitoring a large, rounded object. The object is supported by a base with rollers (90, 92) and a central vertical axis with a rotation handle (32) and a pivot point (34). Six cameras (80) are mounted on the object's surface, each connected to a control unit (40) via a cable (42) and a connector (88). The control units are further connected to a central processing unit (38) via multiple lines. A power source (22) is also shown connected to the system.

FIG. 3

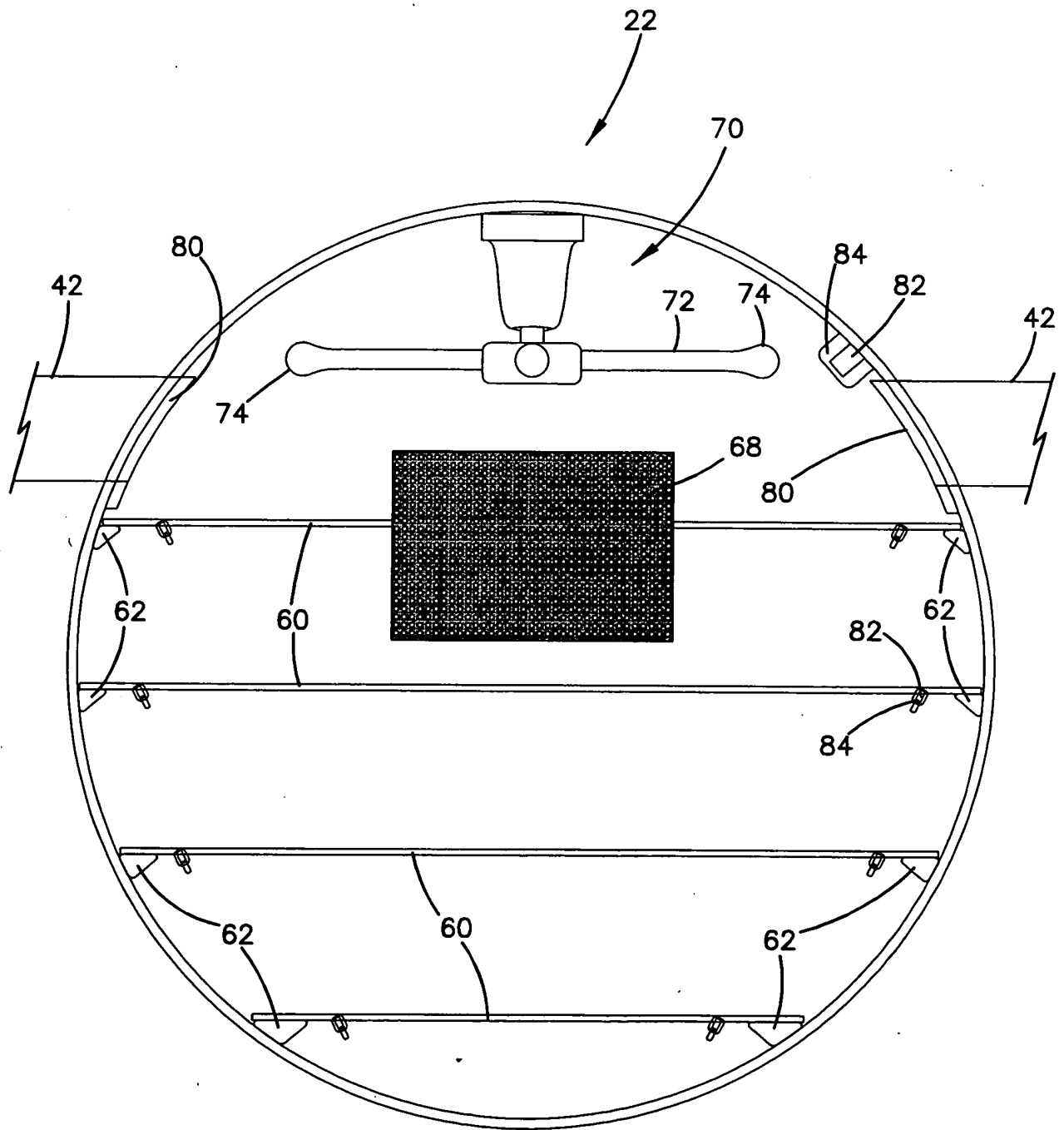


FIG. 4

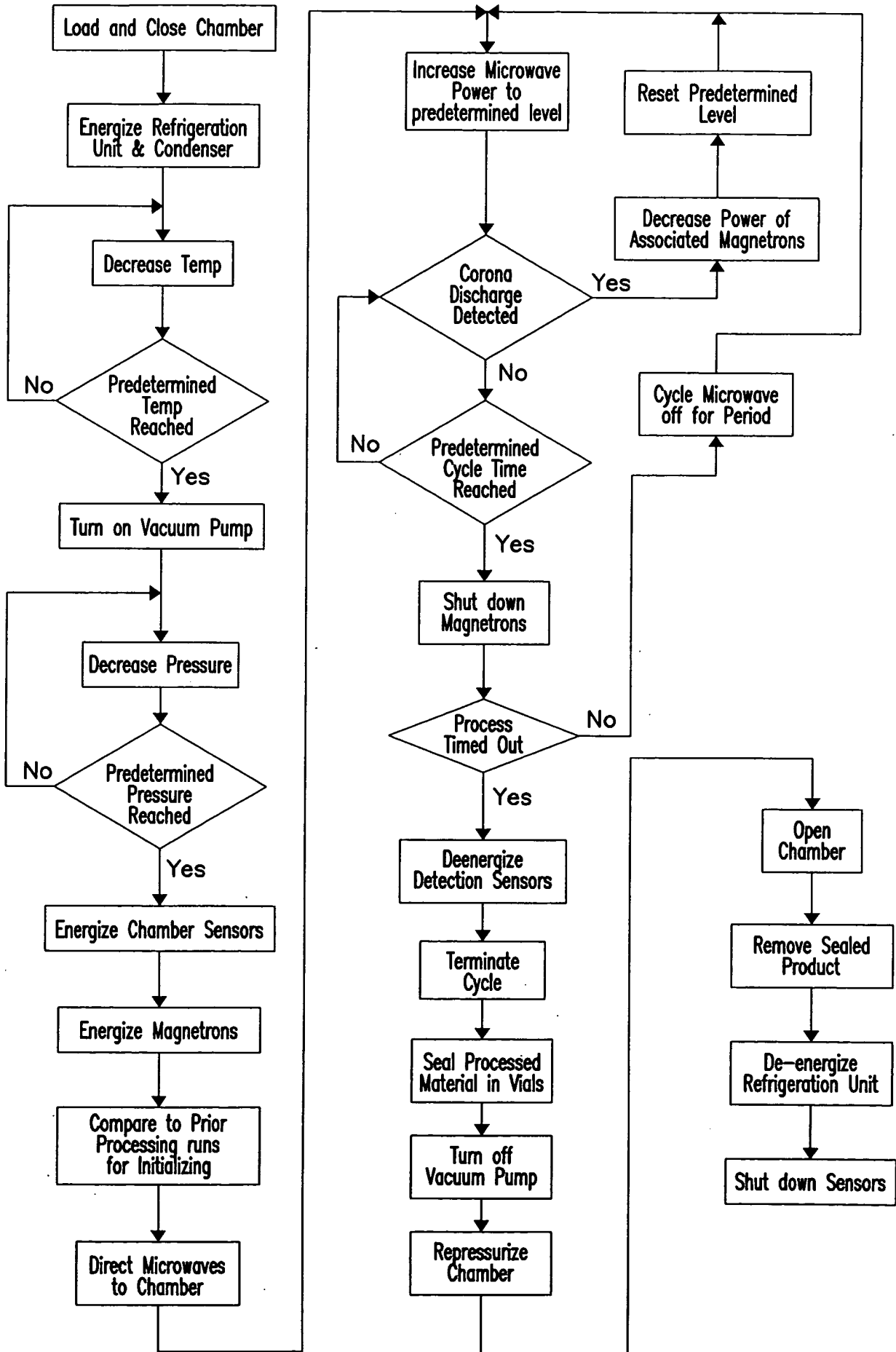
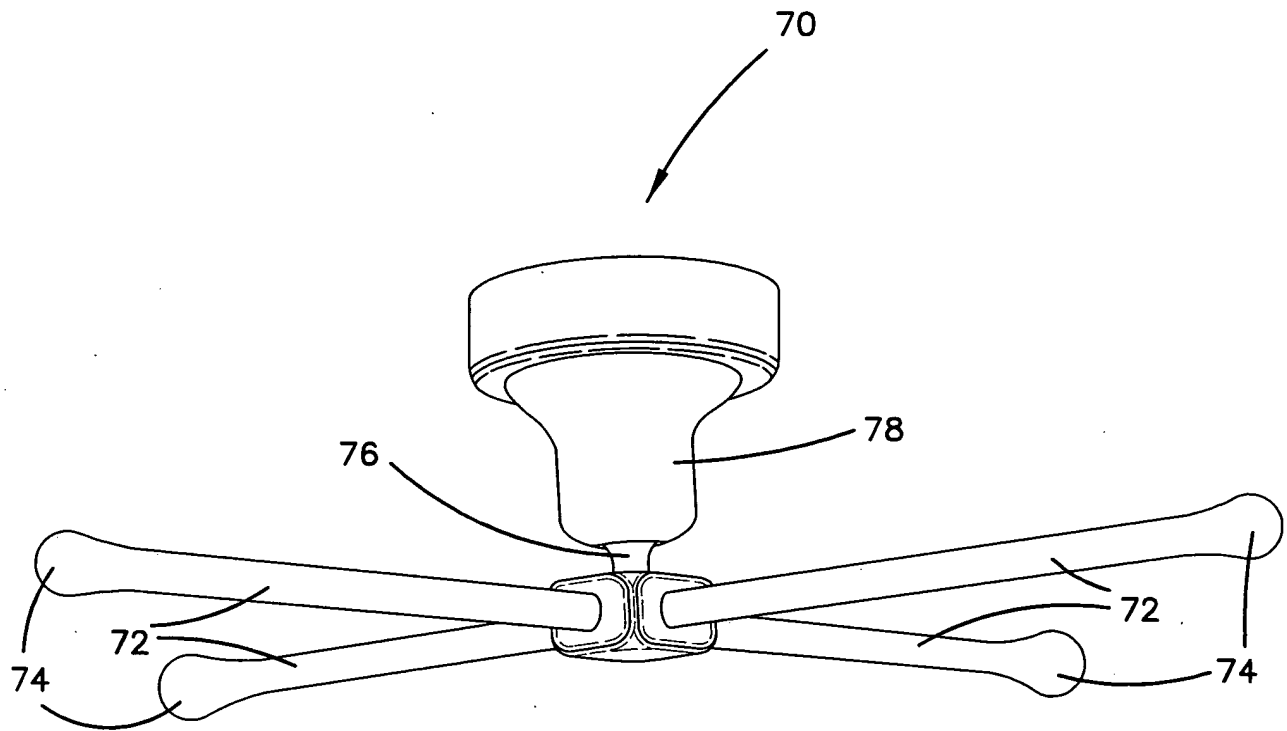
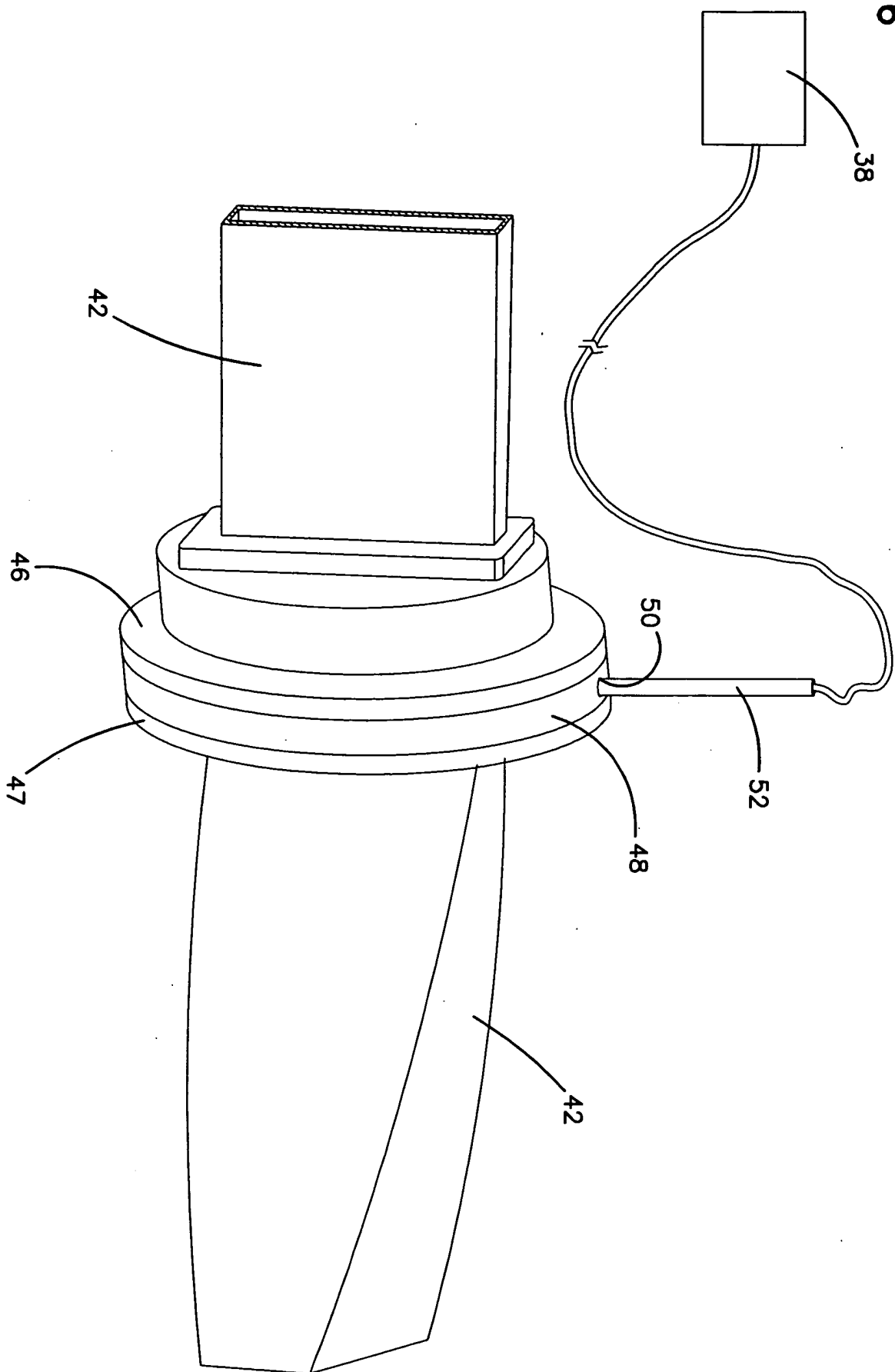


FIG. 5





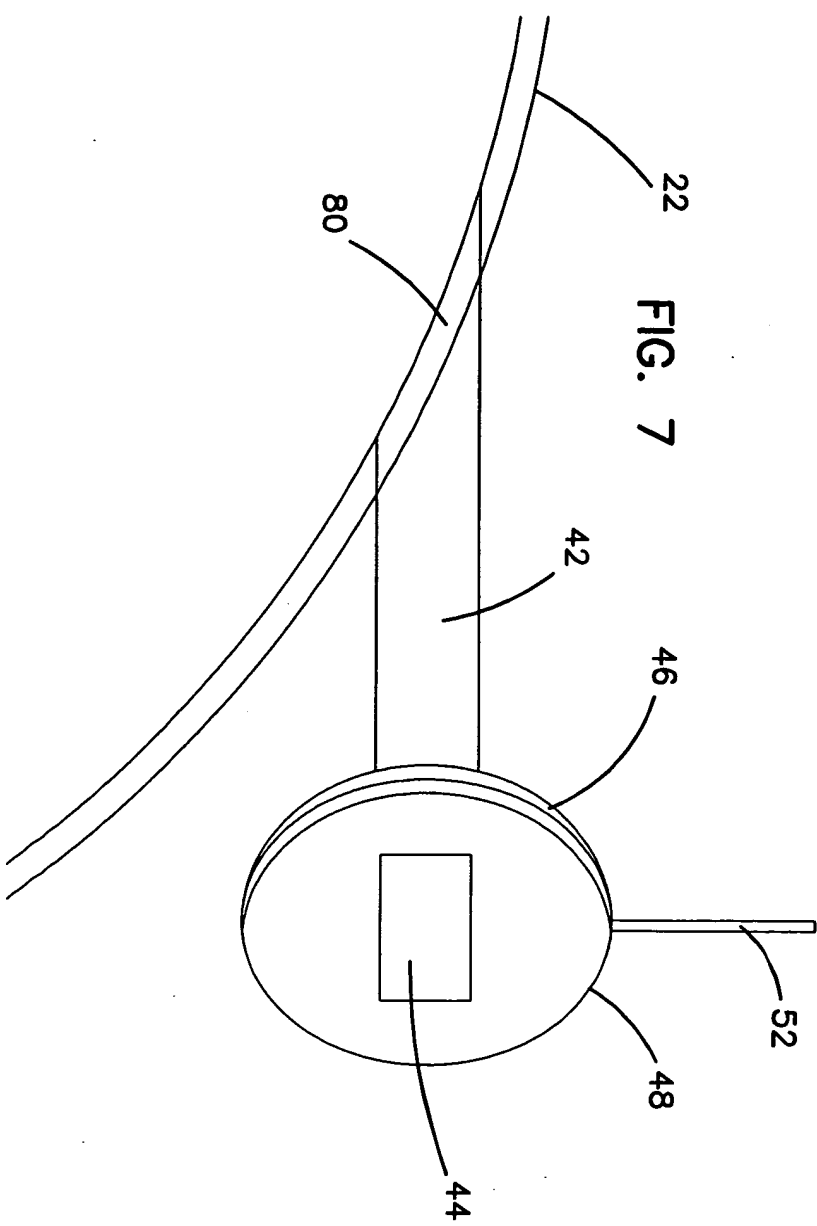


FIG. 8

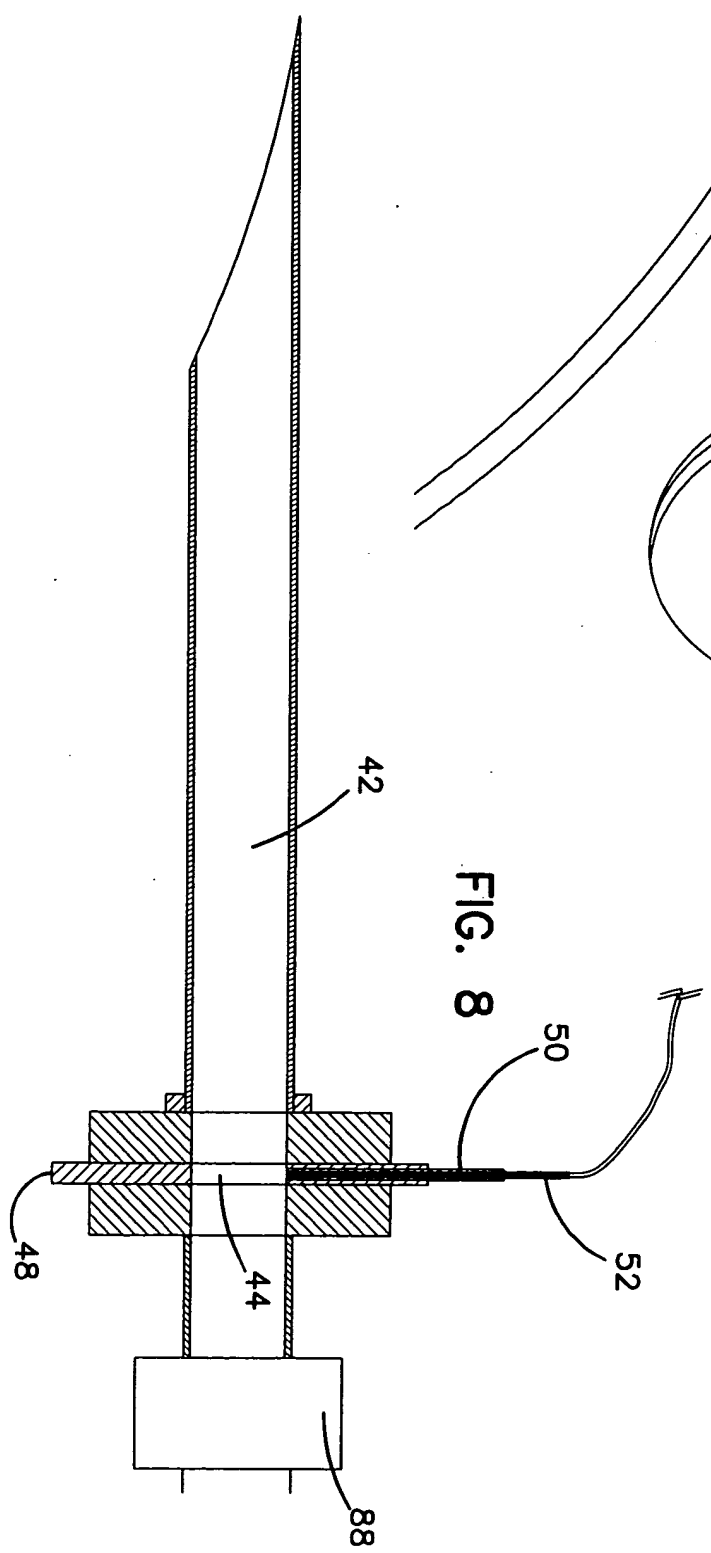


FIG. 9

